ITI 1121. Introduction to Computing II

Binary search tree: concept

by Marcel Turcotte

Version March 27, 2020



Preamble

Overview

Binary search tree: concept

We begin with an overview of the applications of trees in computing: to represent hierarchical data, for compression, and efficient access to elements. We examine the linked implementation of trees. We pay particular attention to binary search trees.

General objective:

This week you will be able to design and modify computer programs based on the concept of a binary search tree.

Preamble

Learning objectives

- Name applications of binary search trees.
- **Describe** the essential properties of binary search trees.

Readings:

Pages 257-268 and 282-296 of E. Koffman and P. Wolfgang.

Preamble

Plan

Plan

1 Preamble

2 Theory

3 Implementation

4 Methods

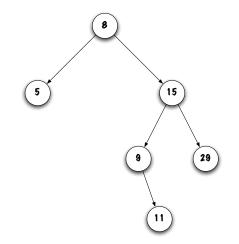
5 Traversing a tree

6 Prologue



Definition

A **binary tree** is a **hierarchical** data structure such that each **node** stores one **value** and has at most two children, called **left** and **right**.

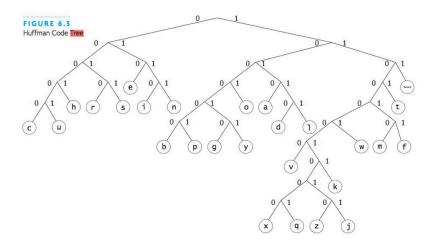




Applications

Applications (general trees)

- Represent hierarchical information such as hierarchical file systems (HFS) (directories and subdirectories), programs (parse tree);
- Huffman trees are used to compress information (files);
- The binary tree is an efficient data structure for implementing abstract data types such as heaps, priority queues, associative structures and sets.



However, to *decode* a file of letters and spaces, you walk down the Huffman **tree**, starting at the root, until you reach a letter and then append that letter to the output text. Once you have reached a letter, go back to the root. Here is an example. The substrings that represent the individual letters are shown in alternate colors to help you follow the process. The underscore in the second line represents a space character (code is 111).

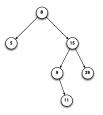
10001010011110101010100010101110100011 g o _ e a g l e s

Source: [1] Figure 6.5.



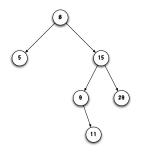
Definitions

Definitions



- All nodes have only one parent, except for one node that has no parent, and is called the root (this is the node at the very top of the diagram);
- Each node has either **0**, **1** or **2** children;
- The childless nodes are the leaves of the tree (or outer nodes);
- The links between the nodes are the **branches** of the tree.

Definitions

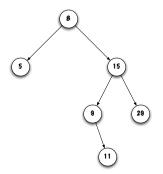


- A node and its descendants are a **sub-tree**;
- The size of a tree is the number of nodes in the tree. An empty tree has a size 0;
- Since we will only deal with binary trees, I will sometimes use the term tree to refer to a binary tree.

We can give a **recursive** definition:

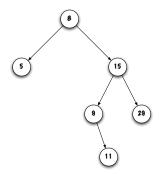
- A binary tree is **empty**, or;
- A binary tree consists of a **value** and **two subtrees** (left and right).

The **node depth** represents the number of links you have to follow from the root in order to access that node. The root is the most accessible node.



What's the depth of the root? The root is always at depth 0.

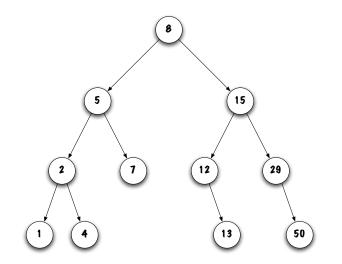
The **node depth** represents the number of links you have to follow from the root in order to access that node. The root is the most accessible node.



The **depth of a tree** is the maximum depth of a node in the tree.

Discussion

All the trees shown here have a property in common. What is it?





A binary search tree is a binary tree whose nodes satisfy the following properties:

- all the nodes of its left subtree have smaller values than this node (or the left subtree is empty);
- all the nodes of its right subtree have greater values than this node (or this subtree is empty).

Corollary: the values are unique.

Implementation

- **How** are we going to implement this class?
- Indeed, we'll use a "nested" and "static" class, Node.
- What are its **instance variables**?
 - The instance variables are: value, left and right;
- What is the type of these variables?
 - > value is of type Comparable, left and right are of type Node.

A static nested class to save a value and create the structure of the tree.

```
public class BinarySearchTree<E extends Comparable<E>>> {
    private static class Node<T> {
        private T value;
        private Node<T> left;
        private Node<T> right;
    }
}
```

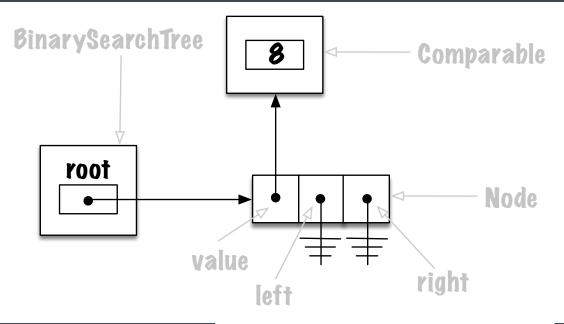
```
What are the instance variables of the BinarySearchTree?
```

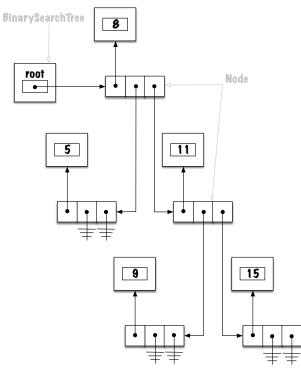
```
public class BinarySearchTree<E extends Comparable<E>>> {
```

```
private static class Node<T> {
    private T value;
    private Node<T> left;
    private Node<T> right;
}
```

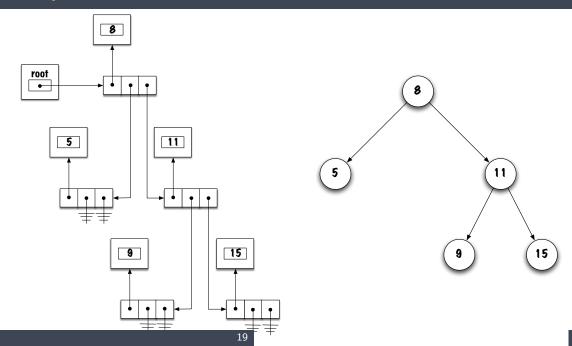
```
private Node<E> root;
```

Memory diagram



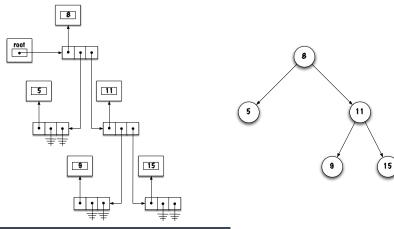


Representations



Observations

- A leaf is a node such that its two descendants are both null.
- The variable **root** can be **null**, so the tree is empty and of size 0.
- For the sake of simplicity, I will often use the more abstract representation on the right.

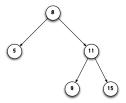


Methods

Methods

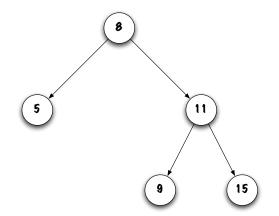
contains

boolean contains(E element)



- 1. Empty tree? element is not found;
- 2. The local root contains **element**? **element** is found; Otherwise? Where are we looking for?
- If element is smaller than the value stored in the current node? Look for element in the left subtree;
- 4. Otherwise (element is necessarily greater than the value in the current node.)? Look for element in the right subtree.

boolean contains(E element)



Exercises: apply the algorithm to find the values 8, 9 and 7 in the tree above.

public boolean contains(E element)

- The presentation suggests a recursive algorithm.
- What will be the signature of the method?

```
public boolean contains(E element) {
    if (element == null) {
        throw new NullPointerException();
    }
    return contains(root, element);
}
```

Like the recursive processing of linked lists, our methods will have two parts, a public part, and a private part whose signature has a parameter of type Node.

boolean contains(Node<E> current, E element)

Base case:

```
if (current == null) {
  result = false;
}
```

but also

```
if (element.equals(current.value)) {
   result = true;
}
```

boolean contains(Node<E> current, E element)

General case: . Search left or right (recursively).

```
if (element.compareTo(current.value ) < 0) {
    result = contains(current.left, element);
} else {
    result = contains(current.right, element);
}</pre>
```

```
private boolean contains(Node<E> current, E element) {
    boolean result;
    if (current == null) {
        result = false;
    } else {
        int test = element.compareTo(current.value);
        if (test == 0) {
            result = true;
        } else if (test < 0) {
            result = contains(current.left, element);
        } else {
            result = contains(current.right, element);
    return result;
```

public boolean contains(E element) (take 2)

- Is the method **boolean contains(E element)** necessarily recursive?
 - No.

Develop a strategy.

- 1. Use a local variable current of type Node;
- 2. Initialize the variable to designate the root node of the tree;
- 3. If current is null then the value is not found, stop;
- 4. If current.value is the value sought, stop;
- 5. If the sought value is smaller than current = current.left, goto 3;
- 6. Else current = current.right, goto 3.

public boolean contains(E element) (take 2)

```
public boolean contains2(E element) {
    boolean found = false:
    Node \langle E \rangle current = root;
    while (! found && current != null) {
        int test = element.compareTo(current.value);
        if (test == 0) {
            found = true:
        } else if (test < 0) {
            current = current.left;
        } else {
            current = current.right;
    return found;
```

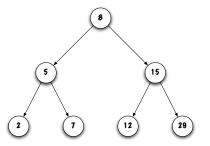
Sometimes one has to **traverse** the tree in order to **visit** all of its nodes.

When **visiting** a node, you perform certain operations on the node.

- Pre-order traversal: visit the root, traverse the left subtree, traverse the right subtree;
- In-order (infix, symmetrical) traversal: traverse the left subtree, visit the root, traverse the right subtree;
- Post-order (suffix) traversal: traverse the left subtree, traverse the right subtree, visit the root;

Exercises

The simplest operation is to display the value stored in the node.



- Give the result displayed for each strategy, pre-order, in-order and post-order.
- What strategy is displaying the data in ascending order?

Pre-order: root, left, right; In-order: left, root, right; Post-order: left, right, root.

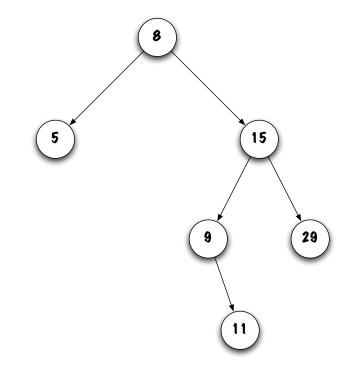
```
private void visit(Node<E> current) {
    System.out.print(current.value);
```

```
public void preOrder() {
    preOrder(root);
}
public void inOrder() {
    inOrder(root);
}
public void postOrder() {
```

postOrder(root);

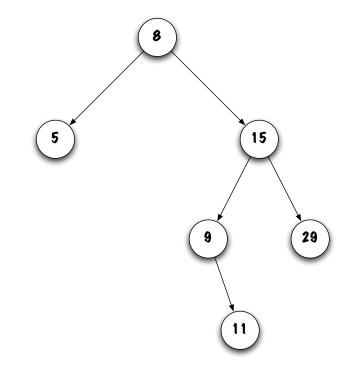
Pre-order

```
private void preOrder(Node<E> current) {
    if (current != null) {
        visit(current);
        preOrder(current.left);
        preOrder(current.right);
    }
}
```



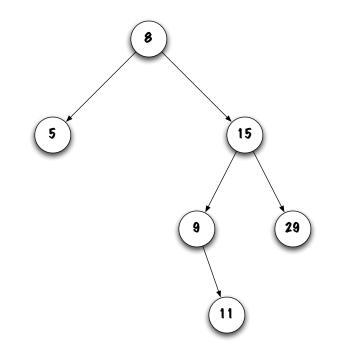
In-order

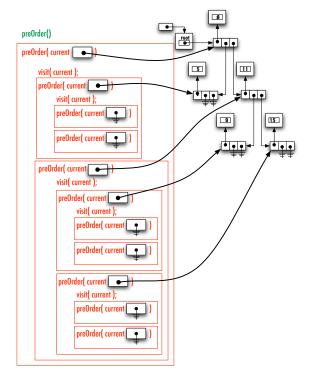
```
private void inOrder(Node<E> current) {
    if (current != null) {
        inOrder(current.left);
        visit(current);
        inOrder(current.right);
    }
}
```



Post-order

```
private void postOrder(Node<E> current) {
    if (current != null) {
        postOrder(current.left);
        postOrder(current.right);
        visit(current);
    }
}
```





- Methods that follow only one path, from the root to a leaf, for example, are easy to implement without recursive calls, see contains;
- Methods that visit several subtrees are often more easily implemented using recursivity.

40



- A **binary search tree** is a binary tree where each node satisfies the following two properties:
 - All the nodes in its left subtree have smaller values than this node's or its left subtree is empty;
 - All the nodes of its **right** subtree have **greater** values than this node or its right subtree is empty.
- Implemented using **linked elements**.

Binary search trees : removal of an element.

References I



E. B. Koffman and Wolfgang P. A. T. Data Structures: Abstraction and Design Using Java. John Wiley & Sons, 3e edition, 2016.

43



Marcel Turcotte

Marcel.Turcotte@uOttawa.ca

School of Electrical Engineering and Computer Science (EECS) University of Ottawa